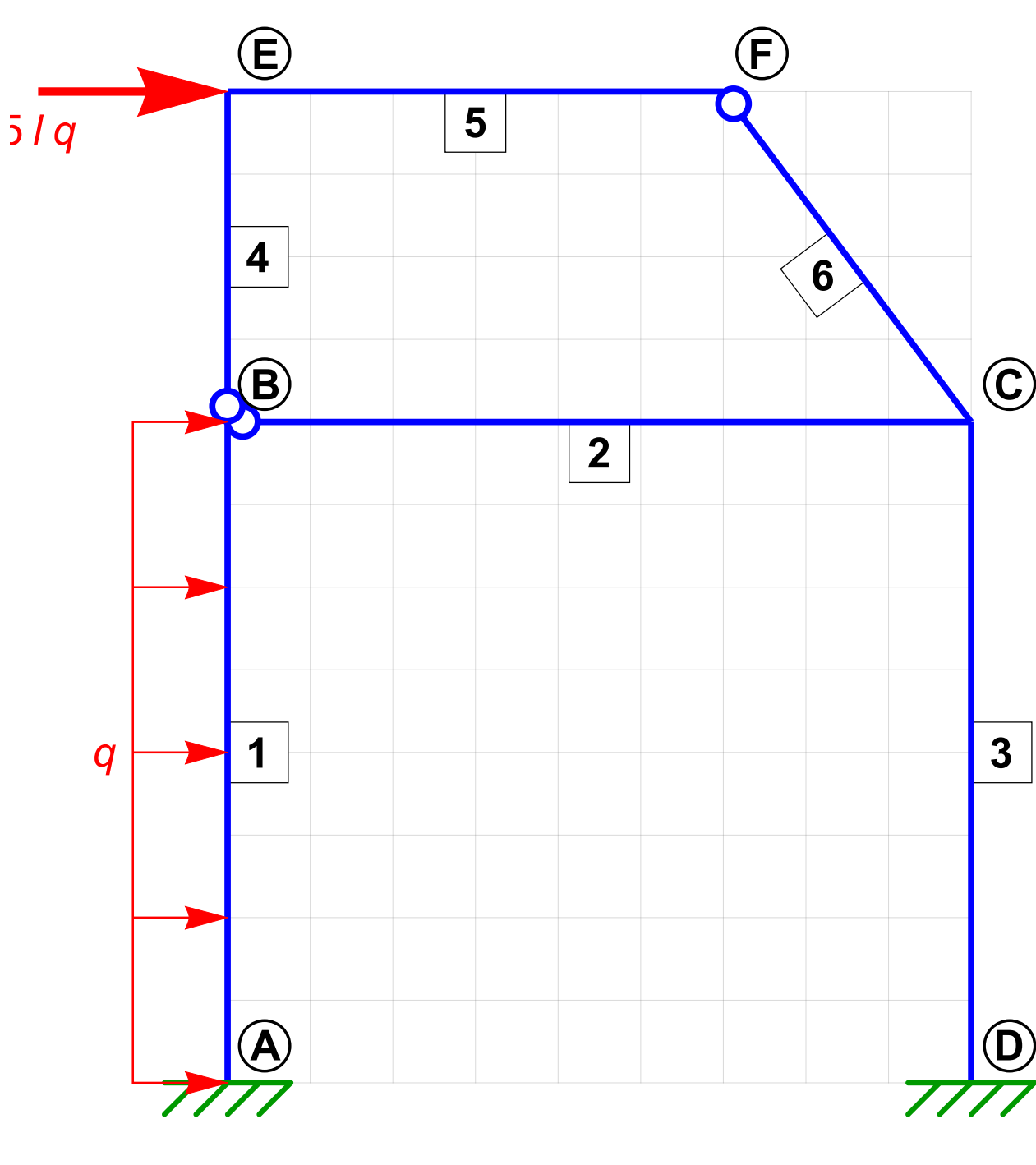


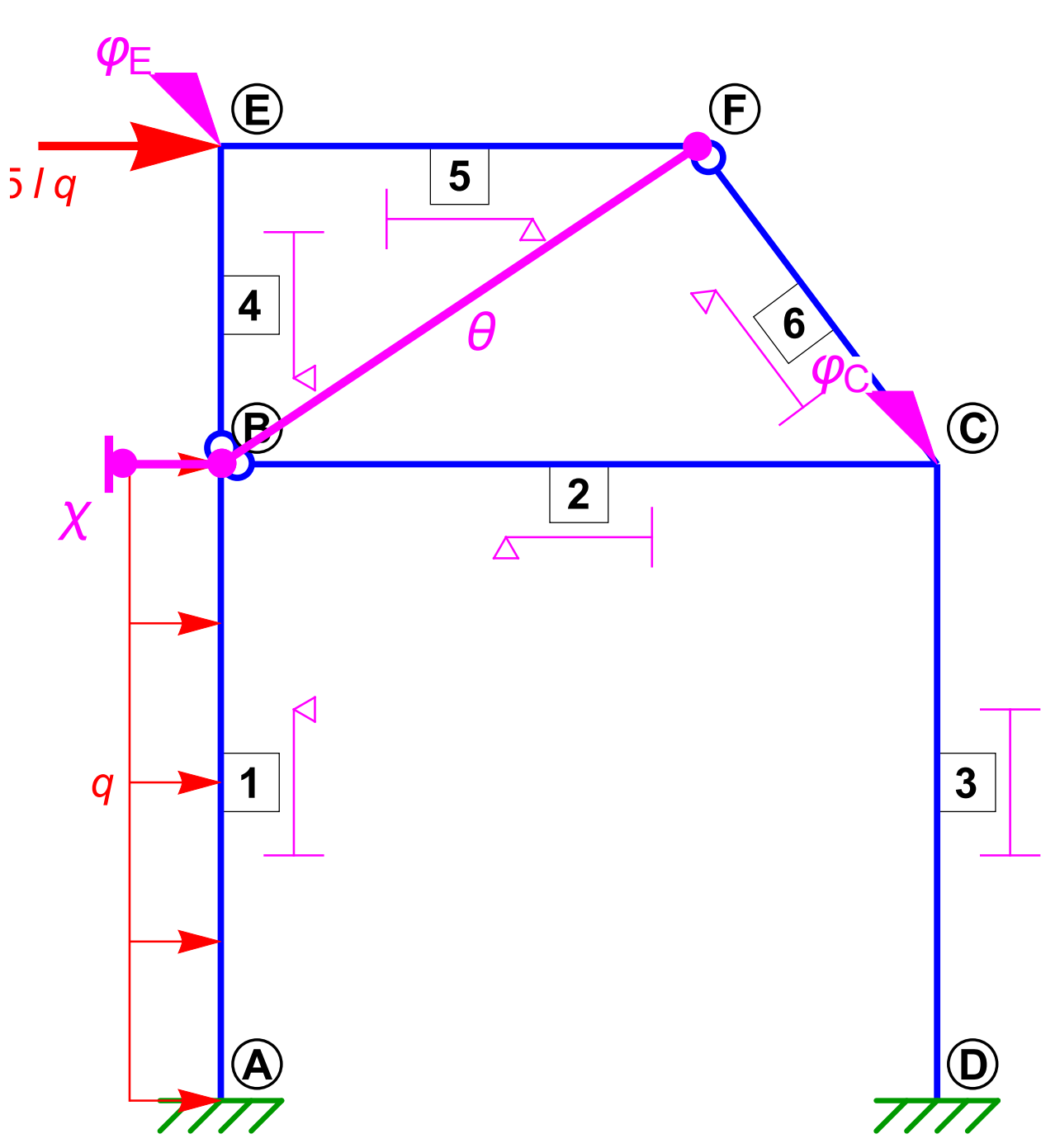
Geometria oraz obciążenia konstrukcji (wymiar oczka siatki – 1):



Wektor niewiadomych:

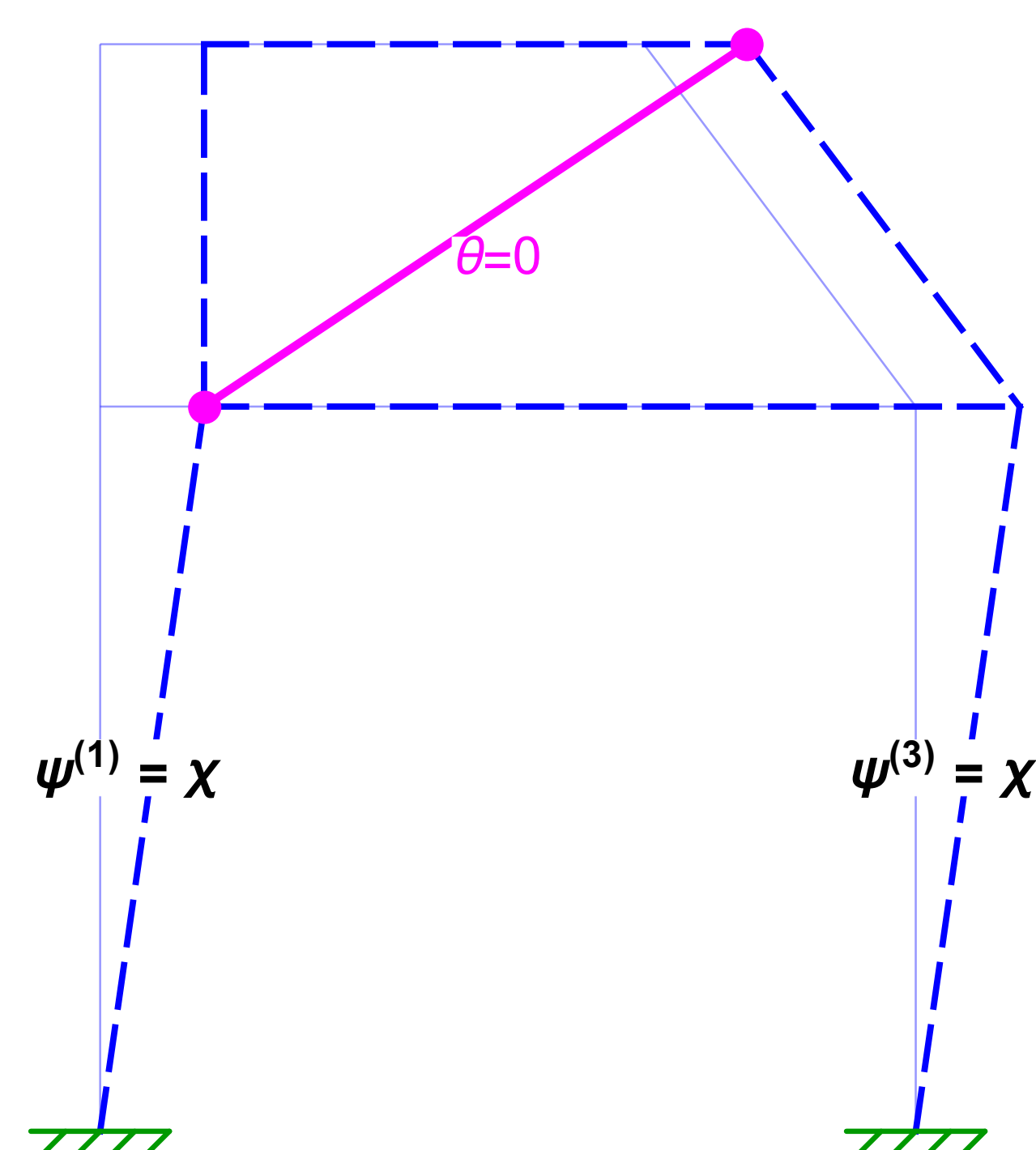
$$\mathbf{q} = \begin{pmatrix} \varphi_E \\ \varphi_C \\ \chi \\ \theta \end{pmatrix}$$

Układ geometrycznie wyznaczalny:

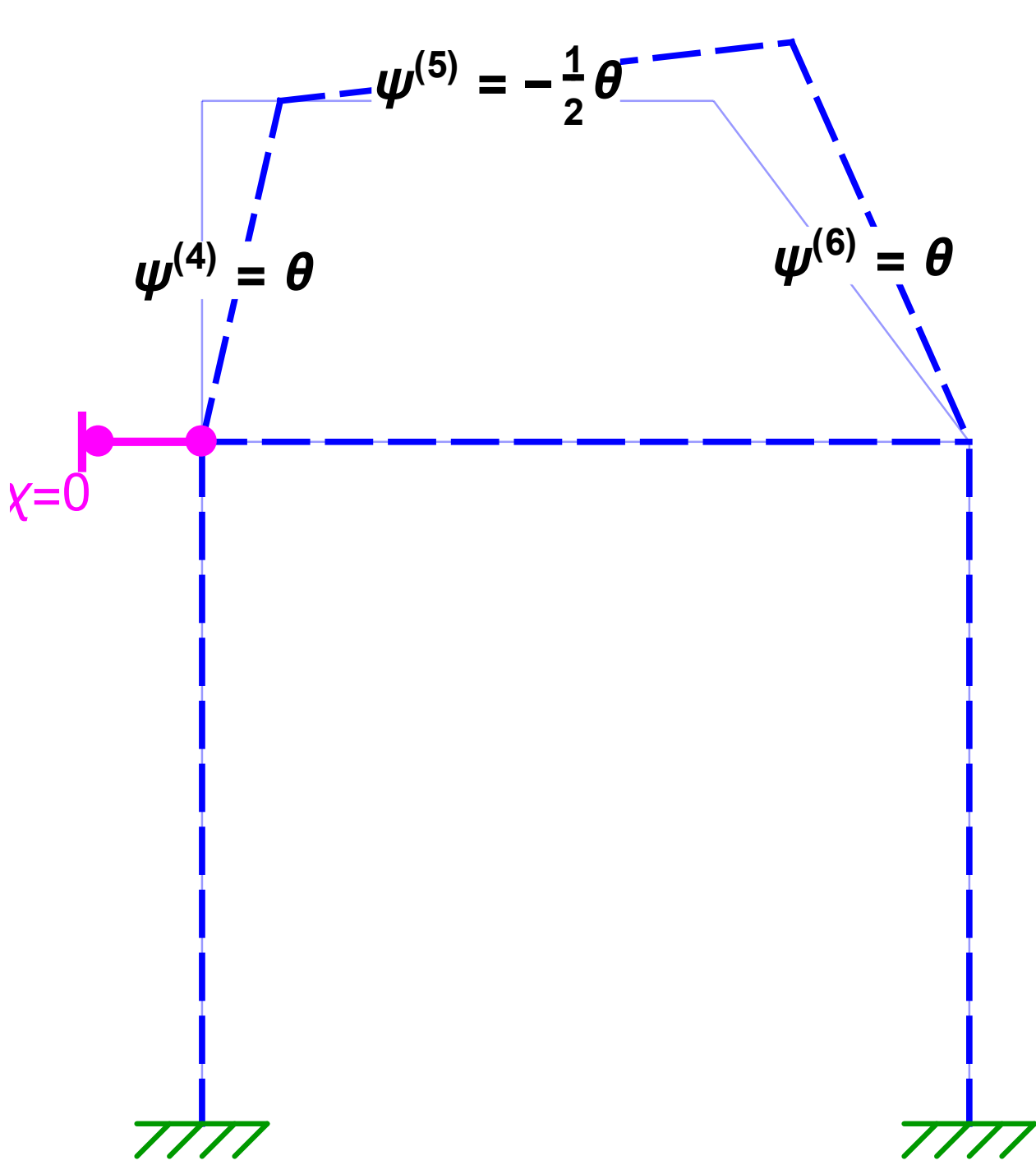


Plany przemieszczeń:

- plan przemieszczeń χ :



- plan przemieszczeń θ :



Ostateczny plan przemieszczeń:

$$\psi^{(1)} = \chi$$

$$\psi^{(2)} = \theta$$

$$\psi^{(3)} = \chi$$

$$\psi^{(4)} = \theta$$

$$\psi^{(5)} = -\frac{1}{2} \theta$$

$$\psi^{(6)} = \theta$$

Momenty wyjściowe:

$$\Phi_A^{01} = -8l^2 q$$

Wzory transformacyjne:

$$\Phi_A^1 = \frac{EJ}{1} \left[-\frac{3}{8} \chi \right] - 8l^2 q$$

$$\Phi_C^2 = \frac{EJ}{1} \left[\frac{1}{3} \varphi_C \right]$$

$$\Phi_D^3 = \frac{EJ}{1} \left[\frac{1}{4} \varphi_C - \frac{3}{4} \chi \right]$$

$$\Phi_C^3 = \frac{EJ}{1} \left[\frac{1}{2} \varphi_C - \frac{3}{4} \chi \right]$$

$$\Phi_E^4 = \frac{EJ}{1} \left[\frac{3}{4} \varphi_E - \frac{3}{4} \theta \right]$$

$$\Phi_E^5 = \frac{EJ}{1} \left[\frac{1}{2} \varphi_E + \frac{1}{4} \theta \right]$$

$$\Phi_C^6 = \frac{EJ}{1} \left[\frac{3}{5} \varphi_C - \frac{3}{5} \theta \right]$$

Równania równowagi:

$$\Phi_E^4 + \Phi_E^5 = 0$$

$$\Phi_C^2 + \Phi_C^3 + \Phi_C^6 = 0$$

$$\Phi_A^1 \cdot \bar{\chi} + (\Phi_D^3 + \Phi_C^3) \bar{\chi} + 51q \cdot 8l \bar{\chi} + 81q \cdot 4l \bar{\chi} = \bar{0}$$

$$\Phi_E^4 \cdot \bar{\theta} + \Phi_E^5 \cdot \left(-\frac{1}{2} \bar{\theta}\right) + \Phi_C^6 \cdot \bar{\theta} + 51q \cdot 4l \bar{\theta} = \bar{0}$$

$$\frac{EJ}{1} \begin{pmatrix} \frac{5}{4} & 0 & 0 & -\frac{1}{2} \\ 0 & \frac{43}{30} & -\frac{3}{4} & -\frac{3}{5} \\ 0 & -\frac{3}{4} & \frac{15}{8} & 0 \\ -\frac{1}{2} & -\frac{3}{5} & 0 & \frac{59}{40} \end{pmatrix} \begin{pmatrix} \varphi_E \\ \varphi_C \\ \chi \\ \theta \end{pmatrix} = l^2 q \begin{pmatrix} 0 \\ 0 \\ 64 \\ 20 \end{pmatrix}$$