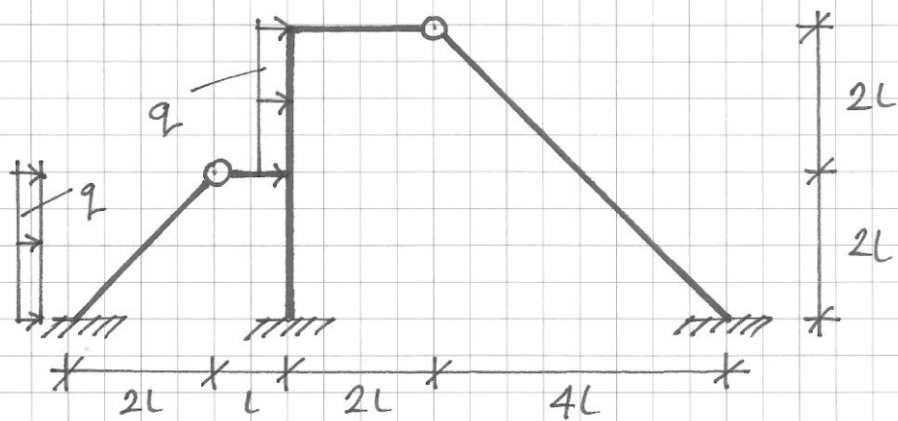


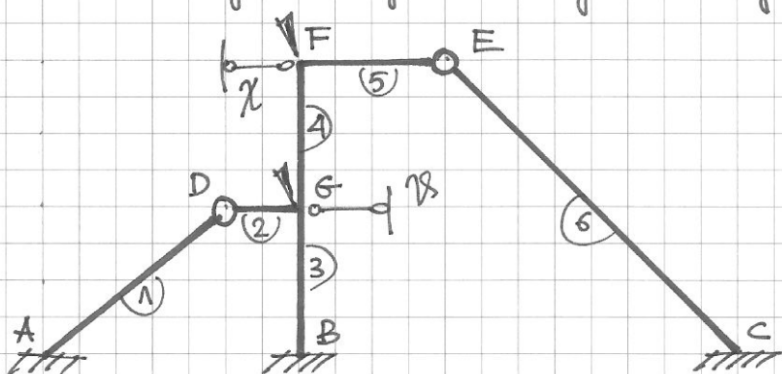
Zapisać równania równowagi Metody Przemieszczeń

$EJ = \text{const.}$

$\sum F = 0 \quad (EA = \infty)$

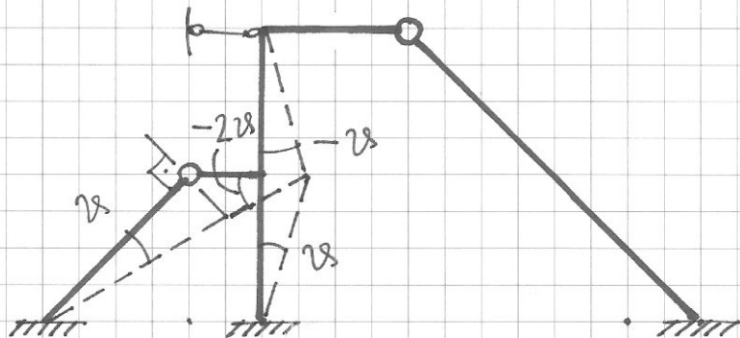


Schemat geometryczne wyznaczamy:



$$q = \begin{bmatrix} \varphi_F \\ \varphi_G \\ \vartheta \\ \chi \end{bmatrix}$$

Plan ϑ :



$\psi(1) = \vartheta$

$\psi(2) = -2\vartheta$

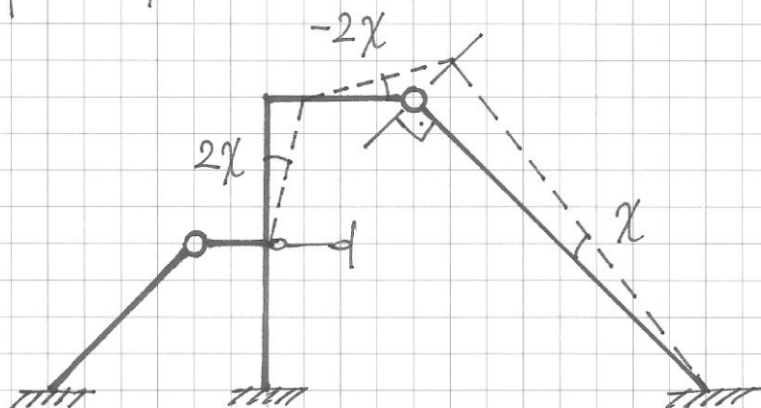
$\psi(3) = \vartheta$

$\psi(4) = -\vartheta + 2\chi$

$\psi(5) = -2\chi$

$\psi(6) = \chi$

plan χ :



Równania równowagi:

$$\Phi_F^{(4)} + \Phi_F^{(5)} = 0$$

$$\Phi_G^{(2)} + \Phi_G^{(3)} + \Phi_G^{(4)} = 0$$

$$\Phi_A^{(1)} \cdot \bar{v} + \Phi_G^{(2)} \cdot (-2\bar{v}) + [\Phi_B^{(3)} + \Phi_G^{(3)}] \cdot \bar{v} + [\Phi_G^{(4)} + \Phi_F^{(4)}] \cdot (-\bar{v}) + \bar{L}v = 0$$

$$[\Phi_G^{(4)} + \Phi_F^{(4)}] \cdot 2\bar{\chi} + \Phi_F^{(5)} \cdot (-2\bar{\chi}) + \Phi_C^{(6)} \cdot \bar{\chi} + \bar{L}\chi = 0$$

$$\bar{L}v = q \cdot 2L \cdot L \cdot \bar{v} + q \cdot 2L \cdot L \cdot \bar{v}$$

$$\bar{L}\chi = q \cdot 2L \cdot L \cdot 2\bar{\chi}$$

Wzory transformacyjne:

$$\Phi_A^{(1)} = \frac{3EJ}{2L\sqrt{2}} [-v] - \frac{1}{2}ql^2$$

$$\Phi_G^{(2)} = \frac{3EJ}{L} [\varphi_G + 2v]$$

$$\Phi_B^{(3)} = \frac{2EJ}{2L} [\varphi_G - 3v]$$

$$\Phi_G^{(3)} = \frac{2EJ}{2L} [2\varphi_G - 3v]$$

$$\Phi_F^{(4)} = \frac{2EJ}{2L} [2\varphi_F + \varphi_G - 3(-v + 2\chi)] + \frac{1}{3}ql^2$$

$$\Phi_G^{(4)} = \frac{2EJ}{2L} [\varphi_F + 2\varphi_G - 3(-v + 2\chi)] - \frac{1}{3}ql^2$$

$$\Phi_F^{(5)} = \frac{3EJ}{2L} [\varphi_F + 2\chi]$$

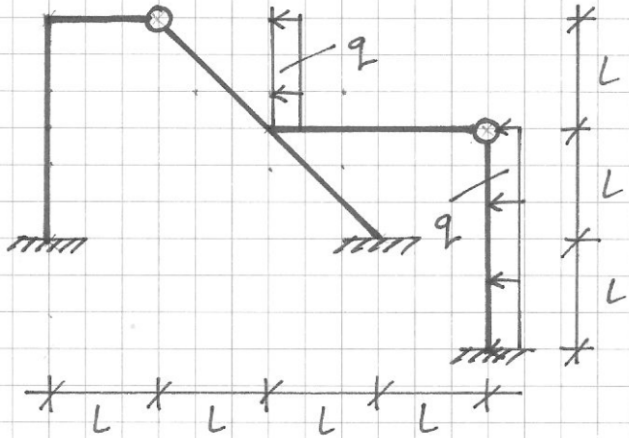
$$\Phi_C^{(6)} = \frac{3EJ}{4\sqrt{2}L} [-\chi]$$

Kolokwium z MK1 2.3b, r.ak. 2014/15

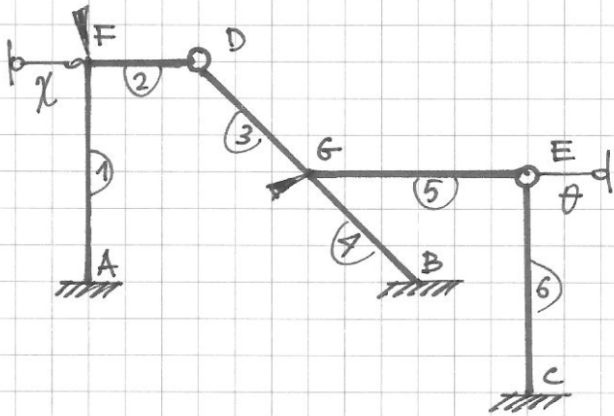
Zapisać równania Metody Przemieszczeń:

$$EI = \text{const.}$$

$$EI = 0 \quad (EA = \infty)$$

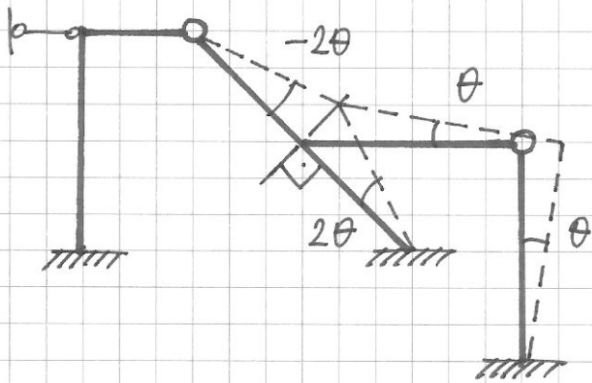


Schemat geometrycznie wyznaczalny:

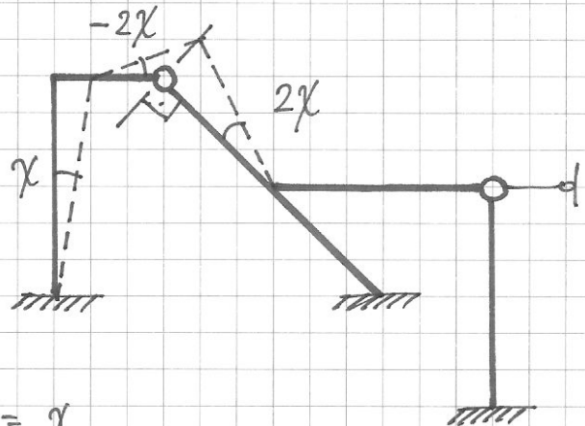


$$q = \begin{bmatrix} \varphi_F \\ \varphi_G \\ \theta \\ \chi \end{bmatrix}$$

plan θ



plan χ



$$\psi^{(1)} = \chi$$

$$\psi^{(2)} = -2\chi$$

$$\psi^{(3)} = -2\theta + 2\chi$$

$$\psi^{(4)} = 2\theta$$

$$\psi^{(5)} = \theta$$

$$\psi^{(6)} = \theta$$

Równania równowagi:

$$\Phi_F^{(1)} + \Phi_F^{(2)} = 0$$

$$\Phi_G^{(3)} + \Phi_G^{(4)} + \Phi_G^{(5)} = 0$$

$$\Phi_G^{(3)} \cdot (-2\bar{\theta}) + [\Phi_B^{(4)} + \Phi_G^{(4)}] \cdot 2\bar{\theta} + \Phi_G^{(5)} \cdot \bar{\theta} + \Phi_C^{(6)} \cdot \bar{\theta} + \bar{L}_\theta = 0$$

$$(\Phi_A^{(1)} + \Phi_F^{(1)})\bar{\chi} + \Phi_F^{(2)} \cdot (-2\bar{\chi}) + \Phi_G^{(3)} \cdot 2\bar{\chi} + \bar{L}_\chi = 0$$

$$\bar{L}_\theta = -q \cdot L \cdot \frac{1}{2}L \cdot 2\bar{\theta} - q \cdot 2L \cdot L \cdot \bar{\theta}$$

$$\bar{L}_\chi = -q \cdot L \cdot \frac{1}{2}L \cdot 2\bar{\chi}$$

Nzony transformacyjne:

$$\Phi_A^{(1)} = \frac{2EJ}{2L} [\varphi_F - 3\chi]$$

$$\Phi_F^{(1)} = \frac{2EJ}{2L} [2\varphi_F - 3\chi]$$

$$\Phi_F^{(2)} = \frac{3EJ}{L} [\varphi_F + 2\chi]$$

$$\Phi_G^{(3)} = \frac{3EJ}{L\sqrt{2}} [\varphi_G + 2\theta - 2\chi] + \frac{1}{8}ql^2$$

$$\Phi_B^{(4)} = \frac{2EJ}{L\sqrt{2}} [\varphi_G - 6\theta]$$

$$\Phi_G^{(4)} = \frac{2EJ}{L\sqrt{2}} [2\varphi_G - 6\theta]$$

$$\Phi_G^{(5)} = \frac{3EJ}{2L} [\varphi_G - \theta]$$

$$\Phi_C^{(6)} = \frac{3EJ}{2L} [-\theta] + \frac{1}{2}ql^2$$