

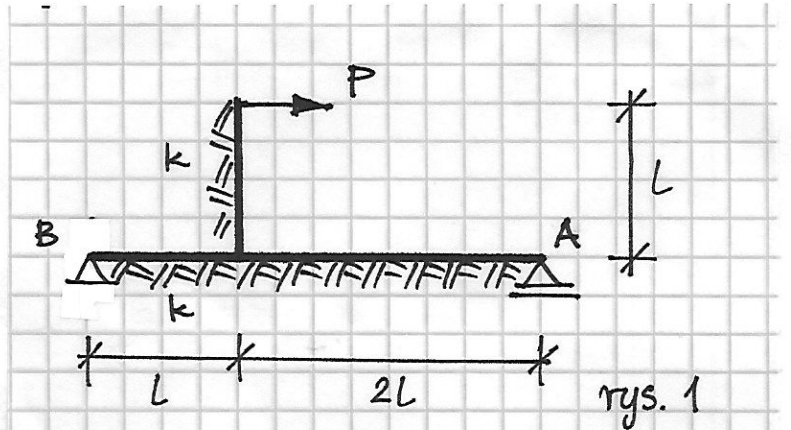
Egzamin z Mechaniki Konstrukcji (MK3 IPB), 8.09.2018
studia niestacjonarne

NAZWISKO, Imię				
rok akademicki zaliczenia ćwiczeń	nr albumu	grupa (IPB / BZ)	tryb studiów (ST / NST)	
ocena zadania 1	ocena zadania 2	ocena zadania 3	ocena egzaminu	ocena łączna

Zadanie 1.

$EJ = const., \quad k = 0,1024 \frac{EJ}{l^4}$

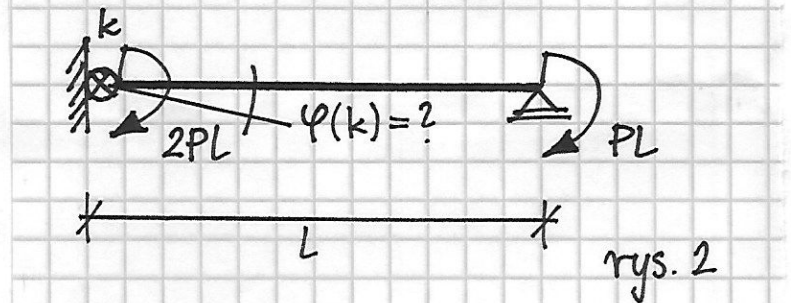
Oblicz poziome i pionowe składowe reakcji podpór A (podpora przesuwna) i B (podpora nieprzesuwna) ramy z rys. 1.



Zadanie 2.

$EJ = const.$

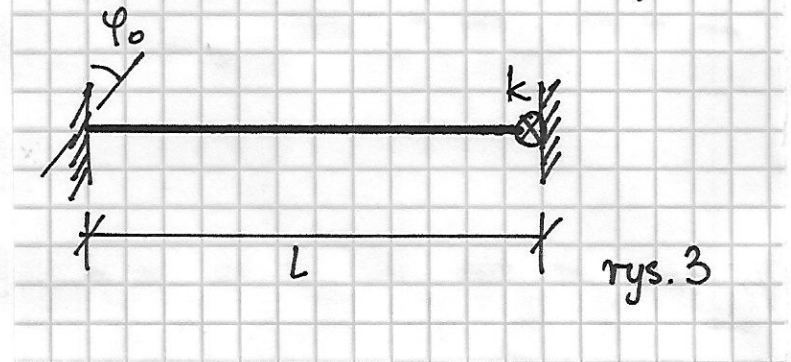
Oblicz wartość $\varphi(k)$ w ramie z rys. 2 dla $k = \frac{EJ}{l}, k = 5 \frac{EJ}{l}, k = 20 \frac{EJ}{l}, k = +\infty$.



Zadanie 3.

Wyprowadź równanie linii ugięcia belki z rys. 3.

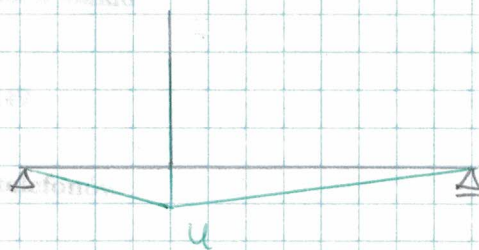
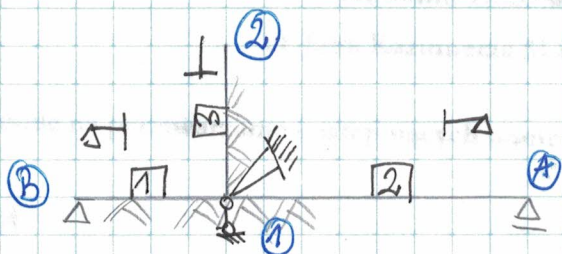
Belka jest obciążona obrotem lewej podpory o kąt φ_0 .



Ugw

$$q = \begin{bmatrix} \varphi \\ \frac{u}{l} \end{bmatrix}$$

Plan przesunięć



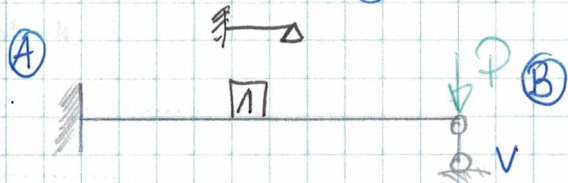
Pręt	$l^{(n)}$	$r^{(n)}$	$*w$	w^*
1	l	0,4	0	u
2	$2l$	0,8	u	0
3	l	0,4	0	0

n.n. MP

$$\bar{\Phi}_1^{(1)} + \bar{\Phi}_1^{(2)} + \bar{\Phi}_1^{(3)} = 0 \quad (1)$$

$$-(W_1^{(1)} \bar{u} + W_1^{(2)} \bar{u}) = 0 \quad (2)$$

Moment wyśkioowy $\bar{\Phi}_1^{(03)}$



$$-W_B^{(1)} \bar{v} + P \bar{v} = 0$$

$$W_B^{(1)} = P$$

$$W_B^{(1)} = -\frac{EY}{l^2} (-\alpha'(0,4) \frac{v}{l}) = 3,024 \frac{EY}{l^3} v = P$$

$$v = 0,331 \frac{Pl^3}{EY}$$

$$\bar{\Phi}_A^{(1)} = \frac{EY}{l} (-\delta'(0,4) \frac{v}{l}) = -0,992 Pl = \bar{\Phi}_1^{(03)}$$

$$W_A^{(1)} = W_1^{(03)} = \frac{EY}{l^2} (-\varepsilon'(0,4) \frac{v}{l}) = -0,488 P$$

Wzory transformacyjne

$$\bar{\Phi}_1^{(1)} = \frac{EY}{l} [\alpha'(0,4) \varphi - \theta'(0,4) \frac{u}{l}] = \frac{EY}{l} [3,002 \varphi - 3,009 \frac{u}{l}]$$

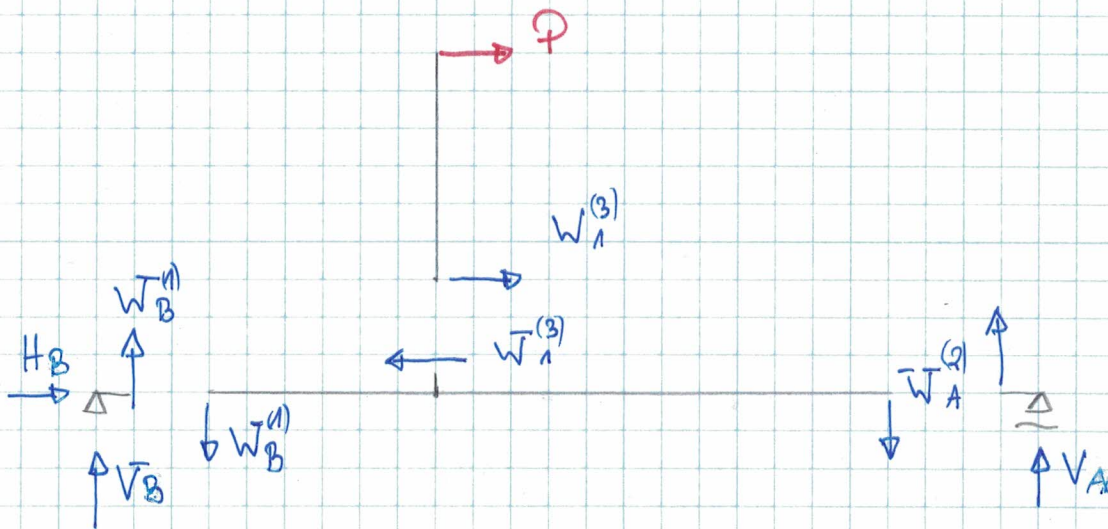
$$\bar{\Phi}_1^{(2)} = \frac{EY}{2l} [\alpha'(0,8) \varphi + \theta'(0,8) \frac{u}{2l}] = \frac{EY}{l} [1,516 \varphi + 0,785 \frac{u}{l}]$$

$$\bar{\Phi}_1^{(3)} = \frac{EY}{e} [\alpha''(0,4)\varphi] - 0,992Pl = \frac{EY}{e} [0,034\varphi] - 0,992Pl$$

$$\bar{W}_1^{(2)} = \frac{EY}{4l^2} [\theta'(0,8)\varphi + \gamma'(0,8)\frac{u}{2l}] = \frac{EY}{e^2} [0,785\varphi + 0,474\frac{u}{e}]$$

$$\bar{W}_1^{(1)} = -\frac{EY}{e^2} [\theta'(0,4)\varphi - \gamma'(0,4)\frac{u}{e}] = \frac{EY}{e^2} [-3,009\varphi + 3,050\frac{u}{e}]$$

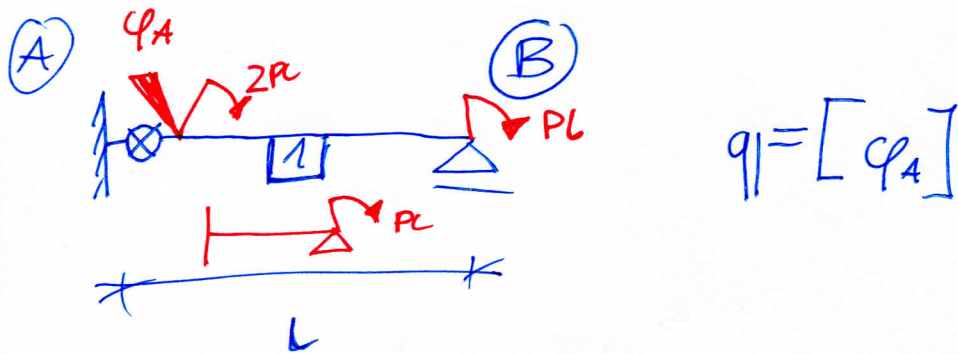
$$\frac{EY}{e} \begin{bmatrix} 4,552 & -2,224 \\ -2,224 & 3,524 \end{bmatrix} \begin{bmatrix} \varphi \\ \frac{u}{e} \end{bmatrix} = \begin{bmatrix} 0,992 \\ 0 \end{bmatrix} Pl \Rightarrow \begin{aligned} \varphi &= 0,315 \frac{Pl^2}{EY} \\ u &= 0,199 \frac{Pl^3}{EY} \end{aligned}$$



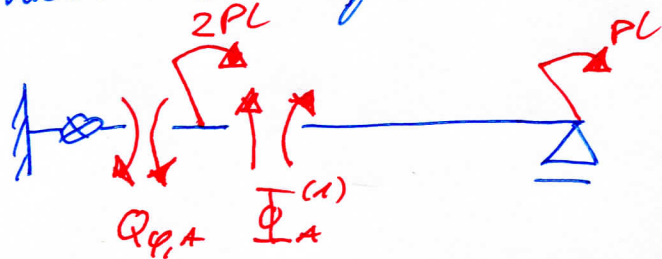
$$H_B = W_1^{(3)} = \frac{EY}{e^2} [\theta''(0,4)\varphi] - 0,988P = -0,972P$$

$$V_B = -W_B^{(1)} = -\frac{EY}{e^2} [\delta'(0,4)\varphi - \epsilon'(0,4)\frac{u}{e}] = -0,350P$$

$$\bar{V}_A = -W_A^{(2)} = \frac{EY}{4l^2} [\delta'(0,8)\varphi + \epsilon'(0,8)\frac{u}{2l}] = 0,300P$$



Równania równowagi MP:



$$1) \Phi_A^{(1)} + Q_{\varphi_A} - 2PL = 0$$

Wzór transformacyjny pręta 1:

$$\Phi_A^{(1)} = \left\{ \begin{array}{c} \varphi_A \\ \Delta \end{array} \right\} = \frac{EJ}{L} [\alpha'(0) \cdot \varphi_A] + \Phi_A^{(0)} = \frac{EJ}{L} [3 \cdot \varphi_A] + \frac{PL}{2}$$

Związek konstytatywny węzła podciężnego:

$$Q_{\varphi_A} = k \cdot \Delta \varphi_A = \left\{ \Delta \varphi_A = \varphi_A - 0 \right\} = \frac{EJ}{L} [\tau \cdot \varphi_A], \text{ gdzie } \tau = \frac{k \cdot L}{EJ}$$

$$1) \frac{EJ}{L} [3 \cdot \varphi_A] + \frac{PL}{2} + \frac{EJ}{L} [\tau \cdot \varphi_A] - 2PL = 0$$

$$\frac{EJ}{L} [(3 + \tau) \cdot \varphi_A] = \frac{3}{2} PL$$

$$\varphi_A = \frac{3}{2(3 + \tau)} \frac{PL^2}{EJ}$$

$$k = \frac{EJ}{L} \Rightarrow \tau = 1 \Rightarrow \varphi_A = \frac{3}{8} \frac{PL^2}{EJ}$$

$$k = 5 \frac{EJ}{L} \Rightarrow \tau = 5 \Rightarrow \varphi_A = \frac{3}{16} \frac{PL^2}{EJ}$$

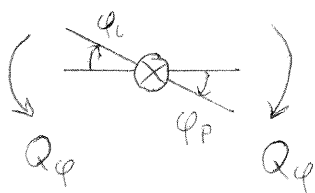
$$k = 20 \frac{EJ}{L} \Rightarrow \tau = 20 \Rightarrow \varphi_A = \frac{3}{46} \frac{PL^2}{EJ}$$

$$k = \infty \Rightarrow \text{z definicji węzeł staje się sztywny} \Rightarrow \varphi_A = 0$$

ZADANIE 3



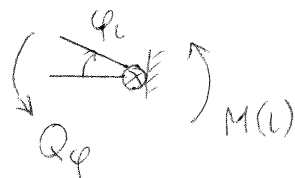
WĘZEL PODATNY:



$$\Delta\varphi = \varphi_p - \varphi_l$$

$$Q_\varphi = k \cdot \Delta\varphi$$

W TYM PRZYPADKU:



$$\Delta\varphi = 0 - \varphi_l$$

$$Q_\varphi = -k \cdot \varphi_l$$

RÓWNANIE RÓŻNICZKOWE:

$$\frac{d^4 w(x)}{dx^4} = 0$$

STĄD:

$$w(x) = C_0 + C_1 x + C_2 x^2 + C_3 x^3$$

$$\varphi(x) = \frac{dw(x)}{dx} = C_1 + 2C_2 x + 3C_3 x^2$$

$$M(x) = -EJ \frac{d^2 w(x)}{dx^2} = (2C_2 + 6C_3 x)(-EJ)$$

SPOSÓB 1:

WARUNKI BRZEGOWE:

(1) $w(0) = 0 \Rightarrow C_0 = 0$

(2) $\varphi(0) = \varphi_0 \Rightarrow C_1 = \varphi_0$

(3) $w(l) = 0$

(4) $M(l) = -Q_\varphi = k \cdot \varphi(l) \Rightarrow -EJ(2C_2 + 6C_3 l) = k(\varphi_0 + 2C_2 l + 3C_3 l^2)$

$$(3) + (4) \Rightarrow \begin{cases} C_2 = -\frac{2\varphi_0(3EJ + kL)}{l(4EJ + kL)} \\ C_3 = \frac{\varphi_0(2EJ + kL)}{l^2(4EJ + kL)} \end{cases}$$

$$w(x) = \varphi_0 x - \frac{2\varphi_0(3EJ + kL)}{l(4EJ + kL)} x^2 + \frac{\varphi_0(2EJ + kL)}{l^2(4EJ + kL)} x^3$$

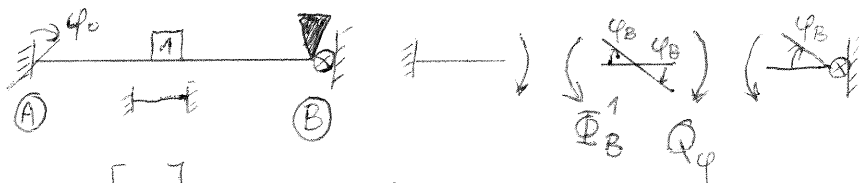
SPOSÓB 2:

(1) $w(0) = 0 \Rightarrow C_0 = 0$

(2) $\varphi(0) = \varphi_0 \Rightarrow C_1 = \varphi_0$

(3) $w(l) = 0$

(4) $\varphi(l) = \varphi_B \leftarrow \text{Z METODY PRZEMIESZCZEŃ}$



$$\varphi_l = [\varphi_B]$$

$$\Phi_B^1 - Q_\varphi = 0$$

$$\Phi_B^1 = \frac{2EJ}{l}(2\varphi_B + \varphi_0)$$

$$Q_\varphi = -k \cdot \varphi_B$$

$$\varphi_B = -\frac{2EJ\varphi_0}{4EJ + kL}$$

$$(4) \varphi_0 + 2C_2 l + 3C_3 l^2 = -\frac{2\varphi_0 EJ}{4EJ + kL}$$

$$(3) + (4) \Rightarrow \begin{cases} C_2 = -\frac{2\varphi_0(3EJ + kL)}{l(4EJ + kL)} \\ C_3 = \frac{\varphi_0(2EJ + kL)}{l^2(4EJ + kL)} \end{cases}$$

$$w(x) = \varphi_0 x - \frac{2\varphi_0(3EJ + kL)}{l(4EJ + kL)} x^2 + \frac{\varphi_0(2EJ + kL)}{l^2(4EJ + kL)} x^3$$